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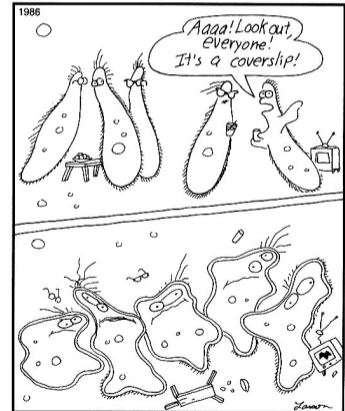
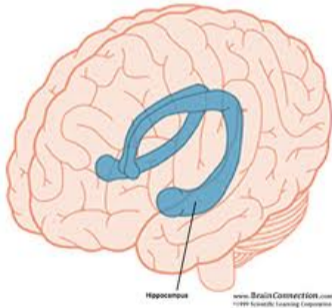
The Czech Academy of Sciences

# **Aplikace typu klient – server (LabVIEW/MATLAB) pro zobrazování hluboko v tkáních**

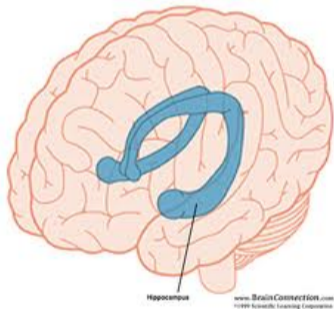
**Martin Šiler**

Akademie Věd ČR, Ústav přístrojové techniky  
Královopolská 147, 612 64 Brno

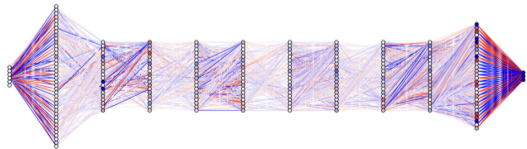
## Co se děje uvnitř živého organismu?



## Co se děje uvnitř živého organismu?



## Jak funguje skutečná neuronová síť?





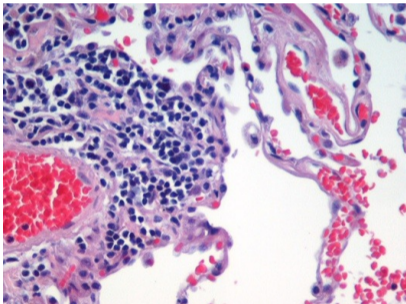




Co se děje uvnitř? **Zajímavé je schované**

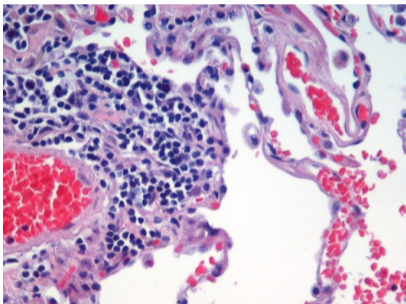


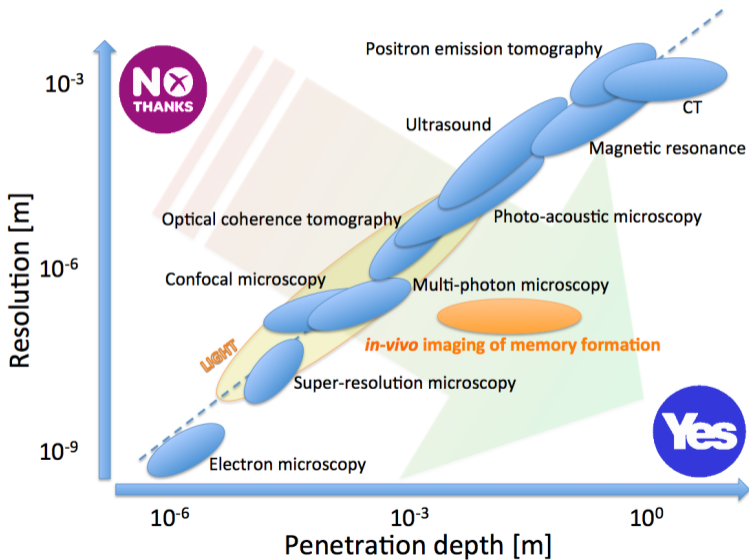
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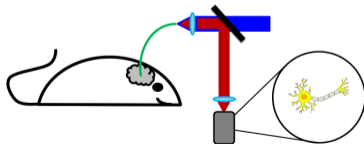
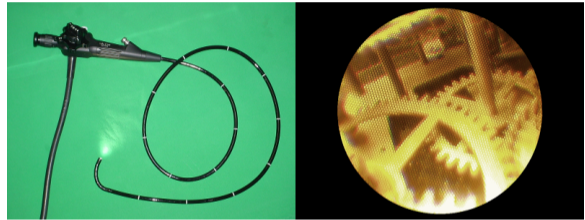
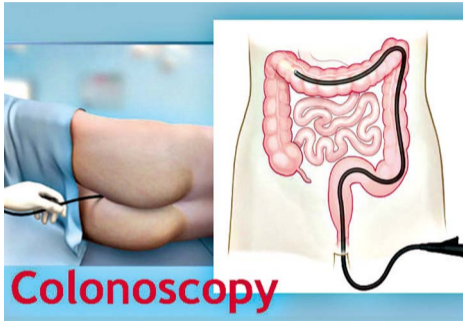




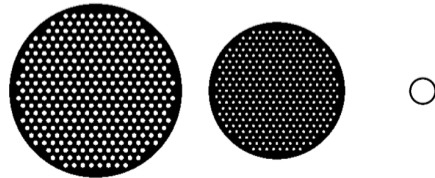
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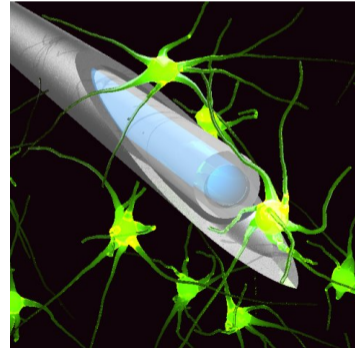
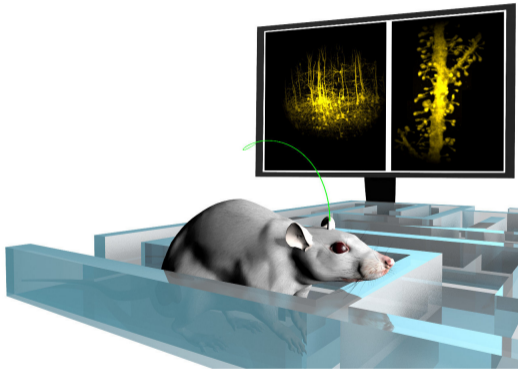


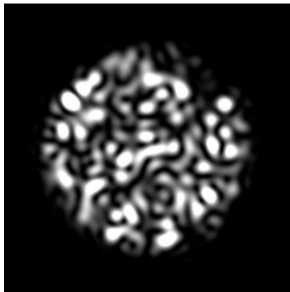
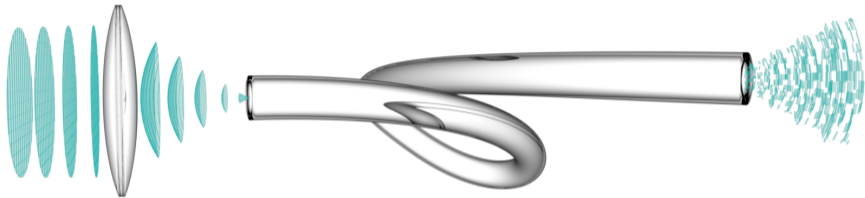


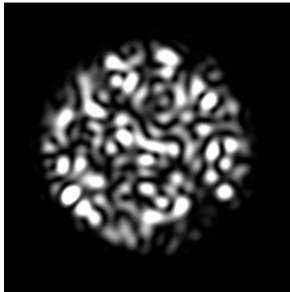
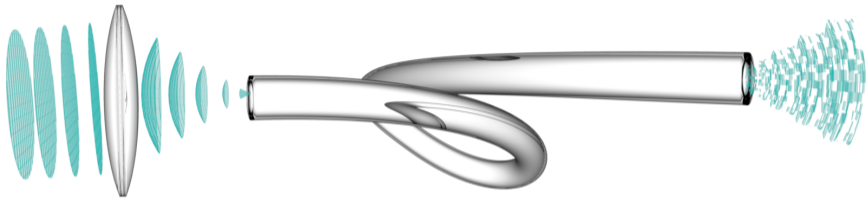


a standard image guide    b single-mode image guide    c multi-mode fibre



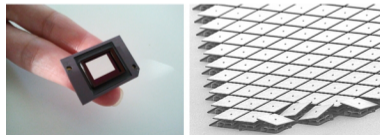
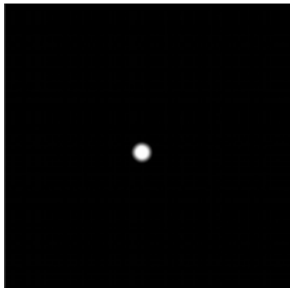
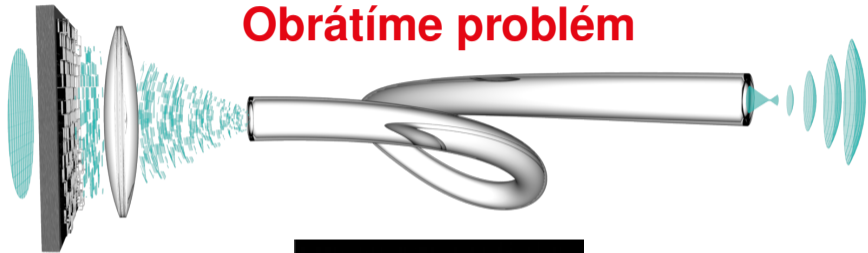


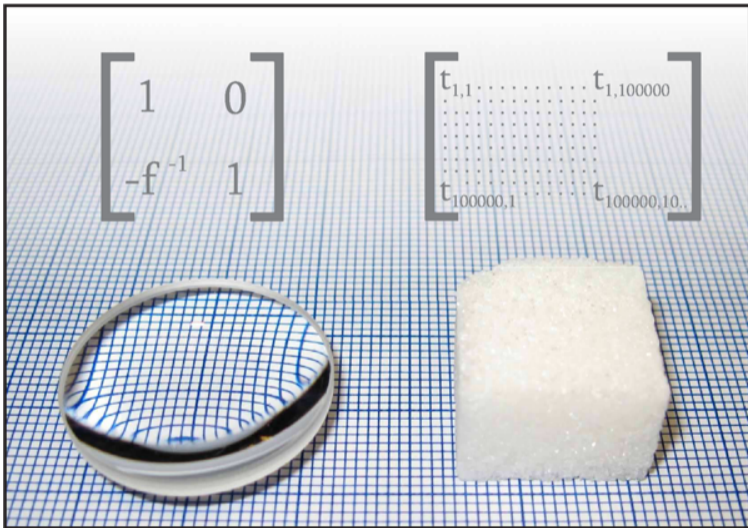




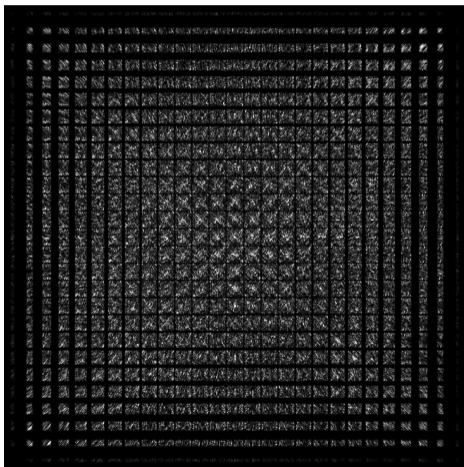
**+ Interference**

## Obrátíme problém

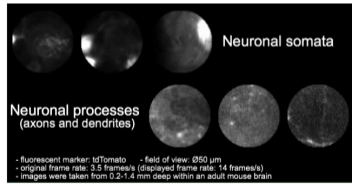
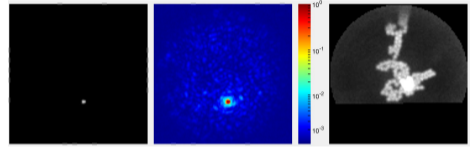
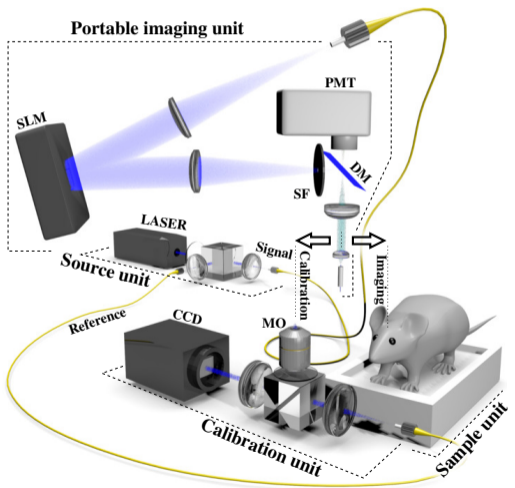


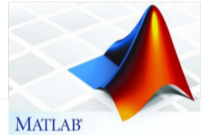
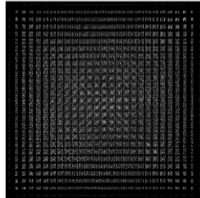
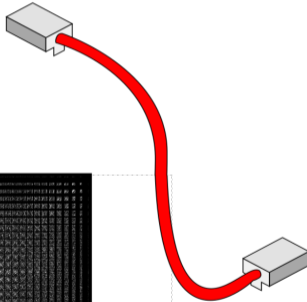
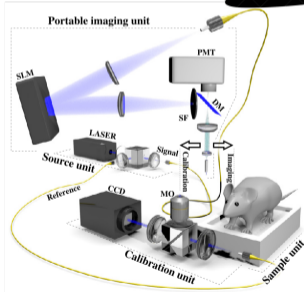
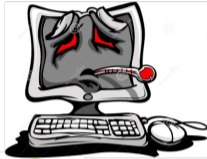






- Propojuje vstup a výstup vlákna
- $65^2 \times 224^2$  complex float  $\Rightarrow$  2 GB  
plánujeme systém s  $16\times$  větší
- vytváří mřížky pro prostorové modulátory
- **Mění se** s teplotou nebo při ohybu vlákna  
 $\Rightarrow$  možné výpočetně kompenzovat





## Server

- 1 Spustí se a naslouchá na daném portu
- 2 Čeká na klienta
- 3 Klient pošle zprávu: co se má dělat a data
- 4 Server vypočítá
- 5 Pošle zpět klientovi
- 6 V klidu se ukončí

## Klient

- 1 Spustí se přihlásí se k serveru
- 2 Pošle zprávu co se má dělat a data
- 3 Počká nž odpověď
- 4 Podle potřeby posílá další
- 5 V klidu se ukončí

## Server

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## Zpráva

Hlavička
Magické číslo Verze protokolu ID sezení Číslo zprávy Velikost dat. bloku
Binární data

## Klient

- 1 Spustí se přihlásí se k serveru
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- 5 V klidu se ukončí

```

classdef gHead
    properties (Constant = true)
        Magic uint32 = 1195463749
        Version uint32 = 1
    end

    methods (Static = true)
        function m = msg(SessionID, CMD, sz)
            m = zeros(1,5, 'uint32');
            m(1) = gHead.Magic;
            m(2) = gHead.Version;
            m(3) = uint32(SessionID);
            m(4) = uint32(CMD);
            m(5) = uint32(sz);
        end
    end
end
end
end

```

```

PORT = 57007;
Socket = tcpip('localhost', PORT, 'NetworkRole', 'server', ...
    'Timeout', 600, 'InputBufferSize', 2^24);
fopen(Socket);

while(1)
    % get header
    hdr = fread(Socket, 5, 'uint32');
    % timeout??
    if isempty(hdr) || numel(hdr) ~=5
        continue
    end
    % check magic
    if hdr(1) ~= gHead.Magic
        % T000 error
    end
    SID = hdr(3);
    CMD = hdr(4);
    SZ = hdr(5);
    % get data
    if SZ > 0
        data = fread(obj.Socket, double(SZ), 'uint8');
    else
        data = [];
    end

    % check version
    if hdr(2) > gHead.Version
        % T000 error
    end

    % Process message
    [replydata, replyhdr] = ProcessMessage(CMD, SID, data);

    % Send Reply
    if ~isempty(replyhdr)
        fwrite(Socket, replyhdr, 'uint32');
        if ~isempty(replydata)
            fwrite(obj.Socket, replydata, 'uint8');
        end
    end

    if CMD == QUIT
        break
    end
end
fclose(Socket);

```

```

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        end
    end
end
  
```

```

PORT = 57007;
Socket = tcpip('localhost', PORT, 'NetworkRole', 'server', ...
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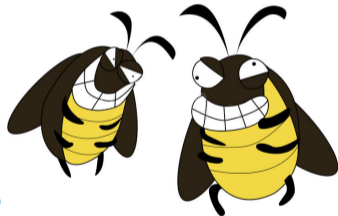
while(1)
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    hdr = fread(Socket, 5, 'uint32');
    % timeout??
    if isempty(hdr) || numel(hdr) ~=5
        continue
    end
    % check magic
    if hdr(1) ~= gHead.Magic
        % TODO error
    end
    SID = hdr(3);
    CMD = hdr(4);
    SZ = hdr(5);
    % get data
    if SZ > 0
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    else
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    % check version
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    % Process message
    [replydata, replyhdr] = ProcessMessage(CMD, SID, data)

    % Send Reply
    if ~isempty(replyhdr)
        fwrite(Socket, replyhdr, 'uint32');
        if ~isempty(replydata)
            fwrite(obj.Socket, replydata, 'uint8');
        end
    end

    if CMD == QUIT
        break
    end
end
fclose(Socket);
  
```





## fread

```
A = fread(FID, size, 'precision');  
A = fread(socket, size, 'precision');
```

soubor: *input*=>*output*

socket: *input*, **výstup vždy double**

\$MATLABROOT/toolbox/shared/instrument/@icinterface/fread.m

```
296 % .....  
297 function dataout = localFormatData(datain, precision)  
298  
299 try  
300     switch precision  
301     case {'uint8', 'uchar', 'char'}  
302         dataout = double(datain);  
303         dataout = dataout + (dataout<0).*256;  
304     case {'uint16', 'ushort'}  
305         dataout = double(datain);  
306         dataout = dataout + (dataout<0).*65536;  
307     case {'uint32', 'uint', 'ulong'}  
308         dataout = double(datain);  
309         dataout = dataout + (dataout<0).*(2^32);  
310     case {'int8', 'schar'}  
311         dataout = double(datain);  
312         dataout = dataout - (dataout>127)*256;  
313     otherwise  
314         dataout = double(datain);  
315     end  
316 catch  
317     dataout = double(datain);  
318 end
```

```
% .....  
function dataout = localFormatData(datain, precision)  
  
try  
    dataout = typecast(datain, precision);  
catch %#ok<CTC>  
    dataout = datain;  
end
```





## Posílání řetězců: Unicode × uint8

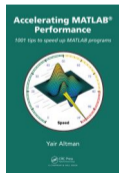
řetězec ⇒ uint8: `unicode2native`  
uint8 ⇒ řetězec: `native2unicode`



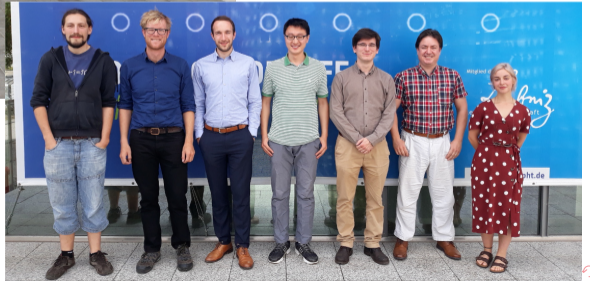
## Co dělat bez Instrument Control Toolboxu

Použít Javu:  
rychlejší, nová havěť

UndocumentedMatlab.com



```
Socket = java.net.ServerSocket;  
Socket.setReceiveBufferSize(int32(2^24));  
Socket.bind(java.net.InetSocketAddress(obj.Port));  
Socket.setSoTimeout(int32(600*1000));  
  
import java.net.ServerSocket  
import java.io.*  
  
socket = obj.Socket.accept;  
outstream = DataOutputStream(BufferedOutputStream(socket.getOutputStream));  
instream = DataInputStream(BufferedInputStream(socket.getInputStream));  
while(1)  
    % get header  
    hdr = zeros(5,1, 'uint32');  
    for kk = 1:5; hdr(kk) = uint32(instream.readInt); end  
  
    SID = hdr(3);  
    CMD = hdr(4);  
    SZ = hdr(5);  
  
    % get data  
    if SZ > 0  
        d0 = org.apache.commons.io.IOUtils.toByteArray(instream, int32(SZ));  
        data = typecast(d0, 'uint8');  
        disp(data);  
    else  
        data = [];  
    end  
  
    % Process message  
    [replydata, replyhdr] = ProcessMessage(CMD, SID, data);  
  
    if ~isempty(replyhdr)  
        for kk = 1:numel(replyhdr)  
            outstream.writeInt(replyhdr(kk));  
        end  
        if ~isempty(replydata)  
            outstream.write(typecast(replydata, 'uint8'), int32(0), replyhdr(5))  
        end  
        outstream.flush;  
    end  
  
    if CMD == gMessage.QUIT  
        break  
    end  
end  
  
socket.close;  
outstream.close;
```



1. **Subcellular spatial resolution achieved for deep-brain imaging in vivo using a minimally invasive multimode fiber**

By: Vasquez-Lopez, Sebastian A.; Turcotte, Raphael; Koren, Vadim; et al.

LIGHT-SCIENCE & APPLICATIONS Volume: 7 Article Number: 110 Published: DEC 19 2018

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2. **High-fidelity multimode fibre-based endoscopy for deep brain in vivo imaging**

By: Turtaev, Sergey; Leite, Ivo T.; Altwegg-Boussac, Tristan; et al.

LIGHT-SCIENCE & APPLICATIONS Volume: 7 Article Number: 92 Published: NOV 21 2018

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3. **Robustness of Light-Transport Processes to Bending Deformations in Graded-Index Multimode Waveguides**

By: Flaes, Dirk E. Boonzajer; Stopka, Jan; Turtaev, Sergey; et al.

PHYSICAL REVIEW LETTERS Volume: 120 Issue: 23 Article Number: 233901 Published: JUN 6 2018

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4. **Three-dimensional holographic optical manipulation through a high-numerical-aperture soft-glass multimode fibre**

By: Leite, Ivo T.; Turtaev, Sergey; Jang, Xin; et al.

NATURE PHOTONICS Volume: 12 Issue: 1 Pages: 33-+ Published: JAN 2018

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5. **Comparison of nematic liquid-crystal and DMD based spatial light modulation in complex photonics**

By: Turtaev, Sergey; Leite, Ivo T.; Mitchell, Kevin J.; et al.

OPTICS EXPRESS Volume: 25 Issue: 24 Pages: 29874-29884 Published: NOV 27 2017

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6. **High-speed spatial control of the intensity, phase and polarisation of vector beams using a digital micro-mirror device**

By: Mitchell, Kevin J.; Turtaev, Sergey; Padgett, Miles J.; et al.

OPTICS EXPRESS Volume: 24 Issue: 25 Pages: 29270-29283 Published: DEC 12 2016

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7. **Multimode fibre: Light-sheet microscopy at the tip of a needle**

By: Ploeschner, Martin; Kollarova, Vera; Dostal, Zbynek; et al.

SCIENTIFIC REPORTS Volume: 5 Article Number: 18050 Published: DEC 14 2015

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8. **Seeing through chaos in multimode fibres**

By: Ploeschner, Martin; Tyc, Tomas; Cizmar, Tomas

NATURE PHOTONICS Volume: 9 Issue: 8 Pages: 529-+ Published: AUG 2015

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9. **Exploiting multimode waveguides for pure fibre-based imaging**

By: Cizmar, Tomas; Dholakia, Kishan

NATURE COMMUNICATIONS Volume: 3 Article Number: 1027 Published: AUG 2012

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10. **Shaping the light transmission through a multimode optical fibre: complex transformation analysis and applications in biophotonics**

By: Cizmar, Tomas; Dholakia, Kishan

OPTICS EXPRESS Volume: 19 Issue: 20 Pages: 18871-18884 Published: SEP 26 2011

[Free Full Text from Publisher](#) [View Abstract](#) ▾

11. **In situ wavefront correction and its application to micromanipulation**

By: Cizmar, Tomas; Mazilu, Michael; Dholakia, Kishan

NATURE PHOTONICS Volume: 4 Issue: 6 Pages: 388-394 Published: JUN 2010



**Tomáš Čižmár, . . . , Martin Šiler**

**[www.isibrno.cz/complexphotonics](http://www.isibrno.cz/complexphotonics)**

*[siler@isibrno.cz](mailto:siler@isibrno.cz)*

*The research was supported by European Structural and Investment Funds Project "Holographic endoscopy for in vivo applications"*

*(No. CZ. 02.1.01/0.0/0.0/15\_003/0000476) and MEYS CR (LO1212).*